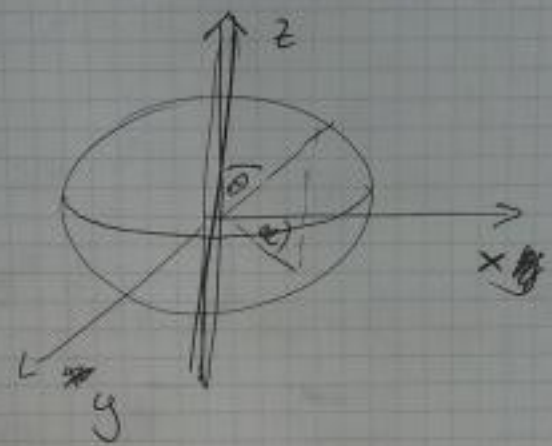


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$$\vec{r} = r \sin\theta \cos\phi \hat{x} + r \sin\theta \sin\phi \hat{y} + r \cos\theta \hat{z}$$

$$dV = r^2 \sin\theta dr d\theta d\phi$$

$$I_z = \int (x^2 + y^2) dm = \int (r^2 \sin^2\theta \cos^2\phi + r^2 \sin^2\theta \sin^2\phi) dm$$

$$= \int r^2 \sin^2\theta dm \quad dm = \rho dV$$

$$I_z = \rho \int_0^R r^4 dr \int_0^\pi \sin^3\theta d\theta \int_0^{2\pi} d\phi$$

$$= \rho \frac{2\pi R^5}{5} \int_0^\pi \sin^3\theta d\theta$$

$\cos\theta = u$  *over aban*

$$du = d(\cos\theta) = -\sin\theta d\theta$$

$$d\theta = -\frac{du}{\sin\theta}$$

$$I_z = \rho \frac{R^5}{5} 2\pi \int_{-1}^1 \sin^2 \theta d\alpha$$

$$= \rho \frac{R^5}{5} 2\pi \int_{-1}^1 (1 - \cos^2 \theta) d\alpha$$

$$= \frac{2\pi \rho R^5}{5} \int_{-1}^1 (1 - \alpha^2) d\alpha = \frac{8}{15} \pi \rho R^5$$

$$M = \frac{4\pi}{3} \rho R^3 \Rightarrow \rho = \frac{3M}{4\pi R^3}$$

$$I_z = \frac{8}{15} \pi \rho R^5 \cdot \frac{3M}{4\pi R^3} = \frac{2}{5} M R^2$$

$R_2$  y'z'ni  $R_1$  u'p o'z'ni p'ot s'p'd  
 L g'ne M g'ne g'ne g'ne g'ne



$R_2$  y'z'ni  $R_1$  u'p o'z'ni p'ot s'p'd

$$M = \int \rho dV = \rho \int_0^L dz \int_0^{2\pi} d\phi \int_{R_1}^{R_2} r dr = \rho L \pi (R_2^2 - R_1^2)$$

$$\rho = \frac{M}{L\pi(R_2^2 - R_1^2)}$$

$$I = \int r^2 dm = \rho \int_0^L dz \int_0^{2\pi} d\phi \int_{R_1}^{R_2} r^3 dr = \frac{M}{\pi L (R_2^2 - R_1^2)} L \pi \cdot \frac{R_2^4 - R_1^4}{4}$$

$$I_z = \frac{M(R_2^2 + R_1^2)}{2}$$